



Results for "((separat\* <sentence> independent\* <sentence> (control\* <or> operat\*)) <and>..."

Your search matched 15 of 1848745 documents.

A maximum of 100 results are displayed, 25 to a page, sorted by Relevance in Descending order.



[Search Options](#)

[View Session History](#)

[New Search](#)

[Key](#)

IEEE JNL	IEEE Journal or Magazine
IEEE JNL	IET Journal or Magazine
IEEE CNF	IEEE Conference Proceeding
IEEE CNF	IET Conference Proceeding
IEEE STD	IEEE Standard

Modify Search

((separat\* <sentence> independent\* <sentence> (control\* <or> operat\*)) <and> ((des

☐ Check to search only within this results set

Display Format: ☒ Citation ☐ Citation & Abstract

[IEEE/ET](#)

[Books](#)

[Educational Courses](#)

[Application Notes](#) |

IEEE/ET journals, transactions, letters, magazines, conference proceedings, and standards.

[view selected items](#)

[Select All](#) [Deselect All](#)

- Performance of an AUV navigation system at Arctic latitudes  
 McEwen, R.; Thomas, H.;  
 OCEANS 2003. Proceedings  
 Volume 2, 22-26 Sept. 2003 Page(s):642 - 653 Vol.2  
 Digital Object Identifier 10.1109/OCEANS.2003.1283346  
[AbstractPlus](#) | Full Text: [PDF](#)(813 KB) [IEEE CNF](#)  
[Rights and Permissions](#)
- Localization and self-calibration of a robot for volcano exploration  
 Caltabiano, D.; Muscato, G.; Russo, F.;  
 Robotics and Automation, 2004. Proceedings. ICRA '04, 2004 IEEE International Conference on  
 Volume 1, 2004 Page(s):586 - 591 Vol.1  
 Digital Object Identifier 10.1109/ROBOT.2004.1307212  
[AbstractPlus](#) | Full Text: [PDF](#)(490 KB) [IEEE CNF](#)  
[Rights and Permissions](#)
- Sensor fusion in mobile robot: some perspectives  
 Gu, J.; Meng, M.; Cook, A.; Liu, P.X.;  
 Intelligent Control and Automation, 2002. Proceedings of the 4th World Congress on  
 Volume 2, 10-14 June 2002 Page(s):1194 - 1199 vol.2  
 Digital Object Identifier 10.1109/WCICA.2002.1020769  
[AbstractPlus](#) | Full Text: [PDF](#)(451 KB) [IEEE CNF](#)  
[Rights and Permissions](#)
- Omega  
 Swanson, E.R.;  
 Proceedings of the IEEE  
 Volume 71, Issue 10, Oct. 1983 Page(s):1140 - 1155  
[AbstractPlus](#) | Full Text: [PDF](#)(1873 KB) [IEEE JNL](#)  
[Rights and Permissions](#)
- Command, control, and navigation experimental results with the NPS ARIES AUV  
 Marco, D.B.; Healey, A.J.;  
 Oceanic Engineering, IEEE Journal of  
 Volume 26, Issue 4, Oct. 2001 Page(s):466 - 476  
 Digital Object Identifier 10.1109/48.972079  
[AbstractPlus](#) | [References](#) | Full Text: [PDF](#)(329 KB) [IEEE JNL](#)  
[Rights and Permissions](#)

6. Location-based services: advances and challenges  
 Adusei, I.K.; Kyamakya, K.; Erbas, F.;  
 Electrical and Computer Engineering, 2004. Canadian Conference on  
 Volume 1, 2-5 May 2004 Page(s):1 - 7 Vol.1  
[AbstractPlus](#) | [Full Text: PDF\(571 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
7. Current developments in underwater vehicle control and navigation: the NPS ARIES AUV  
 Marco, D.B.; Healey, A.J.;  
 OCEANS 2000 MTS/IEEE Conference and Exhibition  
 Volume 2, 11-14 Sept. 2000 Page(s):1011 - 1016 vol.2  
 Digital Object Identifier 10.1109/OCEANS.2000.881732  
[AbstractPlus](#) | [Full Text: PDF\(512 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
8. Vehicle Communications In Europe  
 Bumann, P.;  
 Transportation Electronics, 1988. Convergence 88, International Congress on  
 Oct. 17-18, 1988 Page(s):229 - 235  
[AbstractPlus](#) | [Full Text: PDF\(476 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
9. orig-research  
 TENCON 2005 2005 IEEE Region 10  
 Nov. 2005 Page(s):nil76 - nil291  
 Digital Object Identifier 10.1109/TENCON.2005.301288  
[AbstractPlus](#) | [Full Text: PDF\(194062 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
10. Parallel and distributed simulation  
 Fujimoto, R.M.;  
 Simulation Conference Proceedings, 1995. Winter  
 3-6 Dec. 1995 Page(s):118 - 125  
[AbstractPlus](#) | [Full Text: PDF\(752 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
11. On sensing and control methods for super-mechano colonies  
 Matsuo, Y.;  
 Systems, Man, and Cybernetics, 1999. IEEE SMC '99 Conference Proceedings. 1999 IEEE Inter-  
 Conference on  
 Volume 3, 12-15 Oct. 1999 Page(s):184 - 192 vol.3  
 Digital Object Identifier 10.1109/ICSMC.1999.823176  
[AbstractPlus](#) | [Full Text: PDF\(884 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
12. The vSLAM Algorithm for Robust Localization and Mapping  
 Karlsson, N.; di Bernardo, E.; Ostrowski, J.; Goncalves, L.; Pirjanian, P.; Munich, M.E.;  
 Robotics and Automation, 2005. ICRA 2005. Proceedings of the 2005 IEEE International Confer-  
 18-22 April 2005 Page(s):24 - 29  
[AbstractPlus](#) | [Full Text: PDF\(192 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
13. Team TerraMax and the DARPA grand challenge: a general overview  
 Ozguner, U.; Redmill, K.A.; Broggi, A.;  
 Intelligent Vehicles Symposium, 2004 IEEE  
 14-17 June 2004 Page(s):232 - 237  
 Digital Object Identifier 10.1109/IVS.2004.1336387  
[AbstractPlus](#) | [Full Text: PDF\(865 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)
14. Rapid world modelling from a mobile platform  
 Barry, R.E.; Jones, J.P.; Little, C.Q.; Wilson, C.W.;  
 Robotics and Automation, 1997. Proceedings., 1997 IEEE International Conference on  
 Volume 1, 20-25 April 1997 Page(s):72 - 77 vol.1

Digital Object Identifier 10.1109/ROBOT.1997.620018

[AbstractPlus](#) | [Full Text: PDF\(960 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)

#### 15. Holographic navigation

Rikoski, R.; Brown, D.;

Robotics and Automation, 2008. ICRA 2008. IEEE International Conference on  
19-23 May 2008 Page(s):73 - 80

Digital Object Identifier 10.1109/ROBOT.2008.4543189

[AbstractPlus](#) | [Full Text: PDF\(1717 KB\)](#) | [IEEE CNF](#)  
[Rights and Permissions](#)

[Help](#) | [Contact Us](#) | [Privacy & Security](#) |

© Copyright 2008 IEEE - All Rights Reserved

